

Getting more from simulation – Part 3

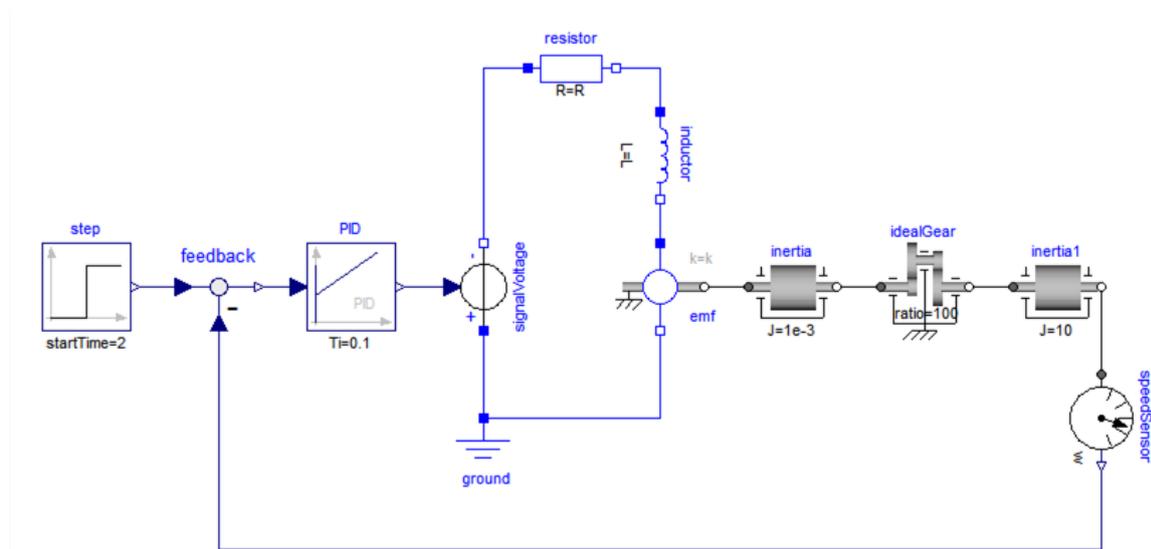
Component orientated modelling versus block diagram modelling

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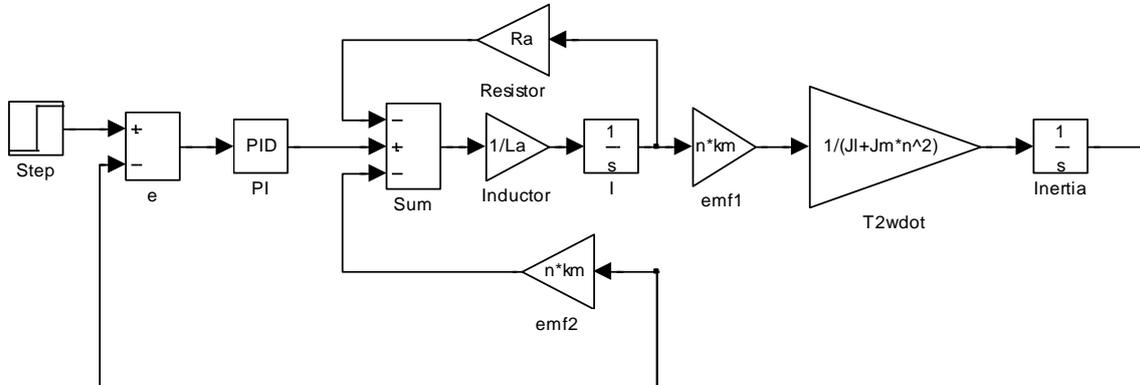
In this 3rd article in the series “Getting more from simulation” we will compare the component orientated, physical modelling approach used in Dymola with the traditional block diagram modelling approach used in tools like Simulink.

Dymola supports a component orientated approach to modelling where each object in the model diagram represents a physical part in the system. Simulink, on the other hand, supports a block diagram approach to modelling that requires the user to manually rearrange the equations defining the system in to a block diagram. The block diagram is then a graphical representation of the equations solved to perform a specific calculation.

The example below illustrates a simple system model built in Dymola. The system consists of an electric motor connected to a 1D rotational inertia and a load inertia via a gearbox. The voltage supplied to the motor is determined using a PID controller that aims to match the rotational speed of the load inertia to the set-point defined in the step function.



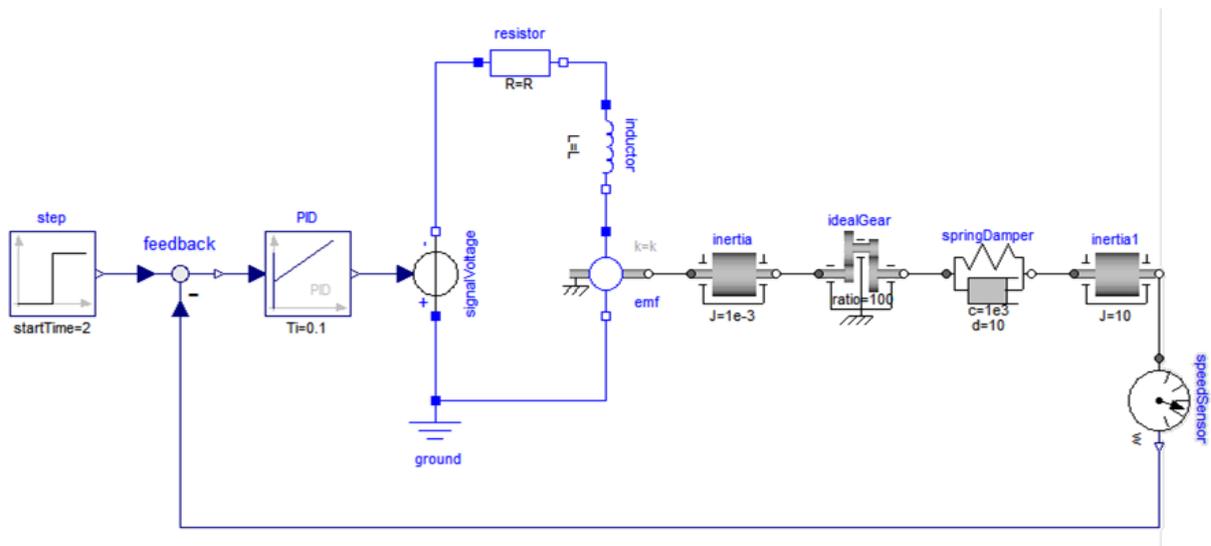
To create the same diagram using a block diagram approach would require the modeller to first determine all the equations required to model each part of the system and to then manually rearrange these in to the correct calculation order. Using Dymola, the process of rearranging the equations is taken care of automatically using symbolic manipulation. Working through this process would yield the following block diagram.



The two models shown above are identical and produce the same results.

The real advantage of the component orientated modelling approach can be realised if we consider what would happen at the next stage of the project. Typically, as a project progresses the models need to include more detail to support the next phase of development. In this example, a simple enhancement that would need to be made to the model is to account for compliance in the gearbox as this would introduce oscillations during transients between the speed set-points.

To make this change using Dymola and the component orientated modelling approach we would simply drag and drop a spring-damper block from the library in to the model and connect it between the gearbox and load inertia as shown below. This change can be accomplished very quickly and the new model can be available in matter of seconds.



To update the block diagram version of the model you would first have to discard half of the model from the first stage because this solution to the model equations doesn't include the compliance in the gearbox. The model developer has to determine the new equations for the compliant system

